

The Priming Function of In-car Audio Instruction

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20 **The Priming Function of In-car Audio Instruction**

21 Studies to date have focused on the priming power of visual road signs, but not
22 the priming potential of audio road scene instruction. Here, the relative priming
23 power of visual, audio and multisensory road scene instructions were assessed. In
24 a lab-based study, participants responded to target road scene turns following
25 visual, audio or multisensory road turn primes which were congruent or
26 incongruent to the primes in direction, or control primes. All types of instruction
27 (visual, audio, multisensory) were successful in priming responses to a road scene.
28 Responses to multisensory-primed targets (both audio and visual) were faster than
29 responses to either audio or visual primes alone. Incongruent audio primes did not
30 affect performance negatively in the manner of incongruent visual or multisensory
31 primes. Results suggest that audio instructions have the potential to prime drivers
32 to respond quickly and safely to their road environment. Peak performance will be
33 observed if audio and visual road instruction primes can be timed to co-occur.

35 Keywords: Auditory priming; visual priming; multisensory priming; driver
36 behaviour

38 Word count: 5,533

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42 **Introduction**

43 The use of in-car navigation systems has grown exponentially during the past few decades,
44 and is expected to continue to grow (Broy, 2006). Traditionally, these systems have been
45 used to provide navigational information to drivers. While these devices have been studied
46 extensively in terms of their potential to distract drivers from the road scene (Dingus,
47 McGehee, Hulse, Jahns & Manakkal, 1995; Srinivasan & Jovanis, 1997; Regan, Oxley,
48 Godley & Tingvall, 2001), or benefit drivers by effectively providing route-guidance
49 information (Barrow, 1991; Fastenmeier, Haller & Lerner, 1994; Burns, 1997; Burnett,
50 2000), little work to date has looked at their potential to directly *prime* drivers to respond
51 quickly and safely to the road environment. Considering the usefulness of other cues such as
52 road signs in priming drivers to respond quickly and effectively to their road environment
53 (Crundall & Underwood, 2001; Koyuncu & Amado, 2008), it is important to explore the
54 potential of in-car devices to do the same.

55 The priming paradigm has become an important tool in measuring how a road cue or
56 device affects driver behaviour. While driving studies had previously focused on a driver's
57 ability to recall or name a road sign (Johansson & Backlund, 1970; Milošević & Gajić, 1986),
58 Fisher (1992) proposed that a more important measure of a road cue's effectiveness is how it
59 affects a driver's response – i.e. the extent to which it can successfully prime a driver such
60 that subsequent responses to the road environment are faster and more accurate. Indeed,
61 implicit measures of a road cue's efficacy are considered to be more useful than measures
62 examining explicit recall or description, as implicit measures are more closely tied to actual
63 modifications in driver behaviour (e.g. slowing down; Summala & Hietamäki, 1984). On this
64 basis, numerous lab-based studies have focused on the implicit processing of road sign
65 information using a priming paradigm (e.g. Crundall & Underwood, 2001; Charlton, 2006;

66 Koyuncu & Amado, 2008). Using this paradigm, a road cue is considered to be effective if its
67 presence facilitates a reaction to a road scene in terms of speed and/or accuracy.

68 Drivers use several cues in order to respond appropriately to the road environment.
69 Road signs are the most frequently used visual primes in preparing drivers to respond
70 (Koyuncu & Amado, 2008), and they play a crucial role in road safety. Indeed, road signs
71 indicating an upcoming intersection or curve in the road can decrease the number of crashes
72 at these sites by as much as 30-40% (Creasy & Agent, 1985; Agent, Stamatidis & Jones,
73 1996). In lab-based studies, both accuracy and response speed are improved by road sign
74 priming. Crundall and Underwood (2001) presented participants with priming images of road
75 signs (“turn left” or “turn right”) followed by images of road bends that were congruent or
76 incongruent in direction. They report that for experienced drivers, congruent road sign
77 priming significantly decreased response time to a subsequent road bend target, relative to
78 incongruent or control priming (see Koyuncu & Amado, 2008 for similar results). Similarly,
79 Charlton (2006) demonstrated that semantic road sign priming increased accuracy and
80 improved response times to images of hazardous road scenes. These studies demonstrate the
81 importance of the priming function of road signs in responding to a road environment.

82 It is becoming increasingly clear that the safest way to present in-car navigational
83 information to drivers is in audio rather than visual form, as in-car glancing to perform
84 secondary tasks such as looking at a GPS device increases drivers’ risk of crashing for both
85 experienced (Klauer, Guo, Sudweeks, & Dingus, 2010; Liang, Lee, & Yekhshatyan, 2012)
86 and novice drivers (Simons-Morton, Guo, Klauer, Ehsani & Pradhan, 2014). The addition of
87 auditory prompts can significantly improve driving performance compared to when
88 information is presented visually on an in-car device (Walker, Alicandri, Sedney & Roberts,
89 1991; Liu, 2001), and this is likely to be due to both a reduction in visual workload (Labaile,

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1990; Walker et al., 1991; Xie, Zhu, Guo & Zhang, 2013) and the reduction in glance-time away from the road scene (Jensen, Skov & Thiruravichandran, 2010). In a comprehensive mixed methods study, Dalton and colleagues (2013) performed the first large-scale investigation of how the auditory presentation of in-vehicle navigational information can affect driving performance. They report a memory advantage and a user preference for auditory over visual presentation of route information. However, that study focused largely on the navigational function, rather than the priming potential of audio presented in-vehicle guidance – an area which has been overlooked in the literature.

 The redundant signals effect (Kinchla, 1974) describes a phenomenon whereby processing is speeded when information is presented in two different sensory channels compared to either channel alone. Whereas a race model (e.g. Raab, 1962) predicts this gain to be a result of activation of the faster of two responses, which are activated separately, Miller’s seminal paper (1982) demonstrated that multisensory input produces processing gains that cannot be explained by separate activation of the single senses involved. Instead, congruent input from different senses *combines* to produce a redundancy gain due to a response threshold being reached more quickly with input from two sources compared to one.

 Indeed, it has been proposed that presenting road environment cues in a multisensory manner – e.g. in both visual and auditory form – should maximise their efficacy (Castro & Horberry, 2005). Multisensory cues are generally better at capturing spatial attention during an attention-demanding task such as driving, compared to either visual or auditory cues alone (see Spence & Santangelo, 2009 for a review), and previous work has shown that the provision of multisensory auditory and vibrotactile cues lead to faster braking times than the presentation of auditory or vibrotactile cues alone (Ho, Reed & Spence, 2007). Of particular interest to driving researchers are the processes contributing to making a decision in a road

environment. The coactivation model outlined by Miller (1982) specifically suggests that the presentation of information in more than one modality should lead to speeded decision responses. As such, the multi-modal presentation of auditory and visual priming information should lead to improved driving performance in response to a road scene target compared to either auditory or visual priming cues alone. A further advantage of presenting road cue information aurally as well as visually is that there is less chance that a solitary visual road sign cue – which may be obscured or not attended to – will be missed.

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122 *Aims and rationale*

123 No research to date has directly compared the effects of visual road sign priming and auditory
124 priming on a road scene task. Considering that over 75% of drivers that use in-car
125 navigational devices utilise the auditory function (Dalton et al., 2013), of interest is whether
126 the addition of an audio prime can strengthen the priming effects traditionally observed for
127 road signs. Similar to the method used by Crundall and Underwood (2001) and Koyuncu and
128 Amado (2008), we used a lab-based priming paradigm to present participants with images of
129 road bend signs followed by semantically related or unrelated images of target road bends.
130 We modified this paradigm to include auditory primes in order to investigate the relative
131 priming power of visual and audio road turn primes. Of interest was whether conventional in-
132 car auditory instruction – “turn left” or “turn right” – primarily used to convey navigational
133 information, could be useful in priming drivers to respond rapidly to a road scene. Finally, we
134 proposed that the concurrent presentation of multisensory visual and auditory road cue primes
135 would produce additional benefit over the presentation of either type of prime alone.

136 In a naturalistic setting, a road turn sign will typically be viewed for 700 ms–1 s (Mori
137 & Abdel-Halim, 1981). We designed our study to mirror this real-world experience closely

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by presenting primes for 580-882 ms. Auditory in-vehicle navigational instructions are often presented 30 s in advance of a road event, with a reminder prompt optimally presented at 4-7 s in advance of a road turn (Green & George, 1995; Wu, Huang & Wu, 2009). We are interested in the potential additional priming function of these instructions if presented at closer temporal proximity to the required road task. We focused here on semantic priming, whereby a road sign or auditory prime is followed by a target road turn image, as this kind of priming is naturally occurring in the driving experience.

Methods

Participants

Thirty-two participants (19 female) with a mean age of 29.3 years (SD = 11.7) volunteered to take part in the study. Participants were required to have a full, clean driving licence with at least two years' driving experience in the UK (average length of experience = 8.6 years, SD = 8.8). This research complied with the American Psychological Association Code of Ethics and received ethical approval from the Psychology Departmental Research Ethics Panel at Anglia Ruskin University. Informed consent was obtained from each participant. Participants were paid £7 for taking part in the experiment.

Stimuli

Prime stimuli for the visual prime condition comprised images of standard UK road signs indicating a left or right bend in the road, taken from the publically available Highway Code: traffic signs publication (Department for Transport, 2007). The control stimulus for this condition was created by replacing the left or right bend arrow in the road sign with "XXX" using Adobe Photoshop. These stimuli were scaled to 600 X 524 pixels. Prime stimuli for the

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3 162 audio prime condition comprised a computer generated voice saying “turn left”, “turn right”
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5 163 or “hello” (control condition). These stimuli were created using free online text-to-speech
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7 164 software and set to speak with a female UK voice, and were converted to mp3 files using
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9 165 Audacity software. Prime stimuli for the multisensory prime condition comprised pairings of
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11 166 visual and audio stimuli. These pairings were always congruent (e.g. the left bend road sign
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13 167 was always accompanied by the audio instruction “turn left”).
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17 168 Target stimuli comprised eight images of local Cambridge road scenes (four rural,
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19 169 four urban) taken in similar lighting conditions using a Nikon D60 camera. The road scenes
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21 170 had a distinct road bend in either the left or right direction and were clear of people and cars.
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23 171 Each road scene was saved in its original form and a mirror reversed form using Adobe
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25 172 Photoshop to create 16 road scenes in total (eight left and eight right bends). These images
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27 173 were converted to greyscale and any distractors (such as road signs visible in the scene) were
28
29 174 removed. The images were then cropped such that the centre of each road bend was central to
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31 175 the image, and were saved at 1100 X 884 pixels. Images were viewed on a 17 inch screen of
32
33 176 a Dell PC. Images subtended a viewing angle of 11.66 by 12.96 degrees (primes) or 18.98 by
34
35 177 23.41 degrees (targets) when viewed from a distance of approximately 70 cm.
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40 41 42 179 ***Procedure***

43 180 Participants ran nine practice trials followed by six blocks of test trials. A trial comprised the
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45 181 presentation of a prime (visual, audio, or multisensory), followed by a fixation cross for 300
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47 182 ms (SOA = 1,182 ms), followed by the presentation of a target stimulus. The visual primes
48
49 183 and the visual element of multisensory primes were always presented for 882 ms, whereas the
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51 184 audio primes and audio element of multisensory primes were presented for 580 ms (“hello”)
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53 185 – 882 ms (“turn left” and “turn right”). In choosing our prime durations, we were guided on
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the literature which showed that road signs are typically viewed for a comparable length of time (700-1,000 ms; e.g. Mori & Abdel-Halim, 1981). While it is difficult to ensure that audio primes using different word have identical durations (in this instance, the congruent and incongruent audio primes had a duration of 882 ms, and the control audio prime had a duration of 580 ms), to counteract against this, SOA's were held strictly at 1,182 ms for all trial types. A prime was followed by a fixation cross, followed by the presentation of a target stimulus. The target stimulus was an image of a road scene, presented until the participant responded. Participants were required to press a button on the keyboard ("z" or "m") to indicate whether the road scene depicted a left turn or a right turn, respectively. Each trial was followed by an inter-trial interval (ITI) varying randomly between 700 and 1,200 ms. See Figure 1 for an illustration of a single trial. Participants were instructed to respond to the road scene as quickly and as accurately as possible. Trials were balanced such that each prime medium type (visual, audio, multisensory) was congruent to the target road scene in direction, incongruent to the road scene in direction, or a control an equal number of times. Trials were presented in a randomised order within each block. Six testing blocks comprised 144 trials each, resulting in 864 trials in total (3 prime types X 3 prime-target congruencies X 16 road scenes X 6 repetitions each).

(Figure 1 goes here)

Results

207 *RT Analyses*

208 Response times for incorrect responses were excluded from analysis and response times
 209 further than 2 SD away from each participant's mean were excluded as outliers (Ratcliff,
 210 1993; 3.96% of correct responses). A 3 X 3 repeated measures ANOVA with factors of
 211 Medium (Visual, Audio, Multisensory) and Prime-Target Congruency (Congruent,
 212 Incongruent, Control) revealed a significant interaction between Prime-Target Congruency
 213 and Medium, $F(4, 124) = 3.27$, $MSE = 136.39$, $p < .05$, $\eta_p^2 = .095$. Follow-up tests were
 214 carried out separately for visual, audio and multisensory prime trials.

215 For trials containing both visual and audio priming information, participants
 216 responded significantly faster where the prime-target information was congruent compared to
 217 when this information was either incongruent, $t(31) = 2.73$, $p < .05$, or control, $t(31) = 2.69$, p
 218 $< .05$. There was no difference in response time to incongruent and control trials, $t(31) =$
 219 1.17 , n.s. All results hold after Bonferroni correction for three comparisons.

220 This pattern was repeated for trials containing only visual primes: responses to
 221 congruent trials were faster than responses to either incongruent, $t(31) = 1.75$, $p < .05$ ($p =$
 222 $.045$; approaches significance following Bonferroni alpha adjustment to $.017$ for three
 223 comparisons), or control trials, $t(31) = 2.77$, $p < .05$ (significant following Bonferroni
 224 correction for three comparisons), with no difference in reaction time between incongruent
 225 and control trials, $t(31) = .06$, n.s.

226 A different pattern was observed for audio prime trials. Here, responses were once
 227 more faster in response to congruent trials compared to either incongruent, $t(31) = 3.48$, $p <$
 228 $.05$, or control trials, $t(31) = 7.03$, $p < .05$. However, responses to incongruent audio prime
 229 trials were significantly faster than responses to control audio prime trials, $t(31) = 2.42$, $p <$

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230 .05. All results hold after Bonferroni correction for three comparisons. See Figure 2 for an
231 illustration of these interaction effects.

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233 (Figure 2 goes here)

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235 Overall, a significant main effect of Prime-Target Congruency was observed, $F(2, 62) =$
236 11.71 , $MSE = 459.10$, $p < .001$, $\eta_p^2 = .274$, with follow up tests showing a straightforward
237 priming effect such that participants responded faster to congruent trials compared to either
238 incongruent trials, $t(31) = 3.06$, $p < .005$, or control trials, $t(31) = 5.26$, $p < .005$. There was
239 no difference in reaction time for incongruent and control trials, $t(31) = 0.60$, n.s. All results
240 hold after Bonferroni correction for three comparisons. See Figure 3 for an illustration of this
241 effect.

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243 (Figure 3 goes here)

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245 A significant main effect of Medium was also observed, $F(2, 62) = 38.72$, $MSE = 243.30$, $p <$
246 $.001$, $\eta_p^2 = .555$. Follow-up tests revealed that participants responded significantly faster on
247 trials where multisensory primes were presented, compared to trials where either visual
248 primes, $t(31) = 6.78$, $p < .001$, or audio primes, $t(31) = 7.71$, $p < .001$, were presented alone.
249 When presented on their own, participants responded faster to trials containing visual primes
250 compared to audio trials, $t(31) = 3.62$, $p < .001$. All results hold after Bonferroni correction
251 for three comparisons. See Figure 4 for an illustration of this effect.

252

253 (Figure 4 goes here)

254

255 ***Accuracy Analyses***

256 As expected with a simple forced-choice task, accuracy performance was close to ceiling
257 (average accuracy = 98.01%, SD = 0.58%). There was no main effect of Medium, $F(2, 62) =$
258 2.70, $MSE = 2.31$, n.s., nor was there an interaction between Medium and Prime-Target
259 Congruency, $F(4, 124) = 1.48$, $MSE = 2.47$, n.s. There was a straightforward effect of Prime-
260 Target Congruency, $F(2, 62) = 7.99$, $MSE = 2.98$, $p < .01$, $\eta_p^2 = .205$, with planned
261 comparisons showing participants scoring significantly less accurately on incongruent trials
262 compared to both congruent trials, $t(31) = 2.52$, $p < .05$, and control trials, $t(31) = 3.56$, $p <$
263 .05. There was no difference in accuracy between congruent and control trials, $t(31) = 1.17$,
264 n.s.

265

266 ***Discussion***

267 In a road scene task, we report strong priming effects for visual road sign primes, audio
268 instruction primes and a combination of both of these types of prime. Responses to a road
269 scene were fastest when priming information was presented concurrently using audio and
270 visual primes, compared to using either visual or audio primes alone. Finally, we report that
271 the presentation of incongruent audio information may not be detrimental to road scene
272 performance in the same way that the presentation of incongruent visual information is.

273 Audio information can be useful in providing navigational information to drivers in a
274 safe manner (Klauer et al., 2010; Liang et al., 2012; Dalton, 2013; Simons-Morton et al.,

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2014). An aim of this study was to investigate whether audio information can also be used to serve a priming function, improving reaction speed to a road scene. We report here that in-car audio priming (e.g. “turn left”) does indeed prompt participants to react more quickly to a subsequent road scene. In demonstrating the priming function of auditory road instruction for the first time, we highlight an additional potential benefit of audio in-car information systems, beyond the provision of navigational information.

A main finding from this experiment is that drivers respond most quickly to a road scene when visual and auditory prompts are presented concurrently. This was expected, considering the general benefits of presenting information in a multisensory manner (e.g. Spence and Santangelo, 2009), including road environment information (Castro & Horberry, 2005). Novel to this study is the suggestion that – in order to be most effective – auditory road environment priming prompts should be timed to coincide with visual road sign prompts wherever possible. This result can be explained in terms of a redundancy gain, whereby the concurrent activation of auditory and visual senses with congruent input lead to a response threshold being reached more quickly compared to when the information was presented in either sensory modality alone (e.g. Miller, 1982).

Because visual road signs elicited faster responses to road scenes than did audio instruction alone, we should be cautious to avoid suggesting that audio primes should supplant visual driving primes. Rather, we highlight the supplementary role that audio information can play in road scene priming – bolstering the effects of visual road sign priming when audio primes are timed to coincide.

In-car audio instruction typically focuses on providing navigational information in a timely manner. In an on-road driving experiment, drivers selected 8-9 s before a turn is required as the ideal presentation time of audio navigation information (e.g. 148 meters from

299 turn at 40 mph; Green & George, 1995). In our experiment, the prime was presented 1.2 s
300 prior to the required road turn. Decreasing the time between a prime and a target is likely to
301 improve its priming efficacy (e.g. Huber & O'Reilly, 2003). However, we should be cautious
302 here and note that drivers need enough time to respond safely to any upcoming road turn. As
303 such, we suggest that two audio prompts be delivered when approaching a road turn: one
304 several hundred meters before the turn (serving a traditional navigational function) and
305 another approximately 1-2 s before the turn response is required (serving the significant
306 priming function that our results suggest). Indeed, this should have a cumulative priming
307 effect, similar to that observed in road sign studies using repetitive priming (e.g. Crundall &
308 Underwood, 2001; Koyuncu & Amado, 2008). Novel to the literature, our results suggest that
309 this will be especially effective when accompanied by a visual road sign instruction; priming
310 timing effects should also be taken into account in road sign placement.

311 In this experiment, we note differential effects for auditory primes compared to visual
312 primes or a multisensory combination of both. While all prime medium types elicit strong
313 priming effects, with congruent primes speeding responses to subsequent road scenes,
314 incongruent primes were less detrimental to performance when information was presented
315 aurally. Specifically, visual and audio-visual combination trials elicited classic priming
316 effects, with fastest responses to congruent trials, followed by control and incongruent trials.
317 For audio trials, a different pattern emerges. Again we see the fastest responses for congruent
318 trials, but incongruent trials elicit *faster* responses than control trials. This suggests that even
319 incorrect audio instruction can prime drivers to respond faster than a neutral phrase. This
320 wasn't the case for trials containing visual information, and we propose that this may be due
321 to the stronger visual ties between a road bend sign and a road bend, compared to the weaker
322 association between the words "turn left" and a left road turn. Additionally, up to one-third of

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323 people may experience mild difficulty when discriminating directional meaning from the
324 words “left” and “right” (McMonnies, 1990), making audio directional instructions a weaker
325 prompt.

326 Alternatively, the instruction to “turn” may provide a priming function in and of itself.
327 That is, the audio command to “turn left” may speed responses because it contains an
328 instruction to act (rather than serving a more descriptive “left turn” function). This might
329 explain why even incongruent audio information (containing the commands “turn left” or
330 “turn right”) led to faster response times than control audio information (“hello”).
331 Interestingly, this does suggest that “getting it wrong” will be less detrimental to driving
332 performance for audio instructions compared to visual instructions.

333 Laboratory driving studies have been found to yield comparable results to real-world
334 driving studies (e.g. Lajunen et al., 1996), and it is considered useful to use lab-based work to
335 understand how drivers extract information from road sign cues (Castro & Horberry, 2004).
336 Indeed, specific perceptual factors can be controlled and manipulated to a much greater
337 extent in a lab setting. As such, much research on the efficacy of road signs is laboratory-
338 based, where we can tightly control variables such as duration of presentation, size, colour
339 and contrast of the sign (Wogalter & Laughery, 1996). In the case of this study, a lab-based
340 experiment facilitated a clean comparison of the relative priming efficacy of different types
341 of driving instruction. However, it is important to acknowledge that in a real-world driving
342 environment, information presented using an in-car device – whether serving a navigational
343 or priming purpose – will be competing for attentional demand with other visual and auditory
344 stimuli. In particular, driving requires that a high level of visual attention be paid to the road
345 scene, relative to auditory information. We should therefore be cautious in emphasising the

346 superiority of visual priming over audio priming for road scenes on the basis of laboratory
347 findings.

348 In-car navigational systems traditionally only provide information when there is a
349 navigational choice to be made. That is, a driver is only presented with visual or audio “turn
350 left” information when faced with a junction or motorway exit. The current study investigated
351 the advantages of audio, visual and multisensory priming where a different type of road
352 response is required – namely responding quickly and accurately to a road bend. Here, we
353 were investigating whether the priming function served by road signs indicating a bend in the
354 road ahead (e.g. Crundall & Underwood, 2001) could be replicated using in-car systems. Our
355 results suggest that this should be the case. The response time advantages this type of priming
356 confers would likely be most useful in precision driving situations. For example, this type of
357 priming should be particularly useful in rally car driving, where extremely fast responses to
358 the road environment are required. The priming function served by presenting this type of
359 priming information – which is functionally different from navigational information currently
360 provided by in-car systems – may confer small advantages in normal driving scenarios as
361 well.

362 Responses in this experimental study were limited to button presses. In part, this
363 design was chosen to control for extraneous perceptual variables in order to make a clean
364 comparison between visual, audio and multisensory road instruction primes, as mentioned
365 above. Another reason for this design choice was to closely replicate the conditions of
366 Crundall and Underwood’s seminal study of the priming function of road signs (2001). In
367 doing so, we could test whether their findings of a priming effect of road signs might extend
368 to in-car audio cues as well, a hypothesis which has not before been tested. Based on our
369 findings, we recommend this as a promising line of investigation, and propose future

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370 simulator and real-world research to further investigate the priming potential of these audio
371 cues.

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373 **Conclusion**

374 With the increased availability of in-car information systems, the question of how these
375 devices can best be used to *prime* drivers to respond, rather than simply provide navigational
376 information, is becoming more pertinent. Our experiment demonstrates the efficacy of audio
377 priming in responding to a road scene and suggests that the concurrent presentation of both
378 visual and audio primes should improve reaction speed in a driving setting. Overall, we
379 suggest a new research direction in the study of in-car information systems focusing on the
380 priming potential of these devices.

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33 508 **Figure Captions**

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35 509 Figure 1: Sequence of trial events. Primes were either visual (road sign), audio (computerised
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37 510 voice), or both (as illustrated in this example).

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Figure 2: Mean response times to correctly respond to a road turn when the prime stimulus
was congruent (diagonal lines) or incongruent (checker) to the target road turn direction, or a
control (dots). Error bars represent the standard error of the mean.

Figure 3: Mean response times to correctly respond to a road turn when the prime stimulus was multisensory (solid grey), visual (vertical lines) or audio (horizontal lines). Error bars represent the standard error of the mean.

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Figure 4: Mean response times to correctly respond to a road turn following a visual prime, multisensory prime or an audio prime when the prime stimulus was congruent (diagonal lines) or incongruent (checker) to the target road turn direction, or a control (dots). Error bars represent the standard error of the mean.

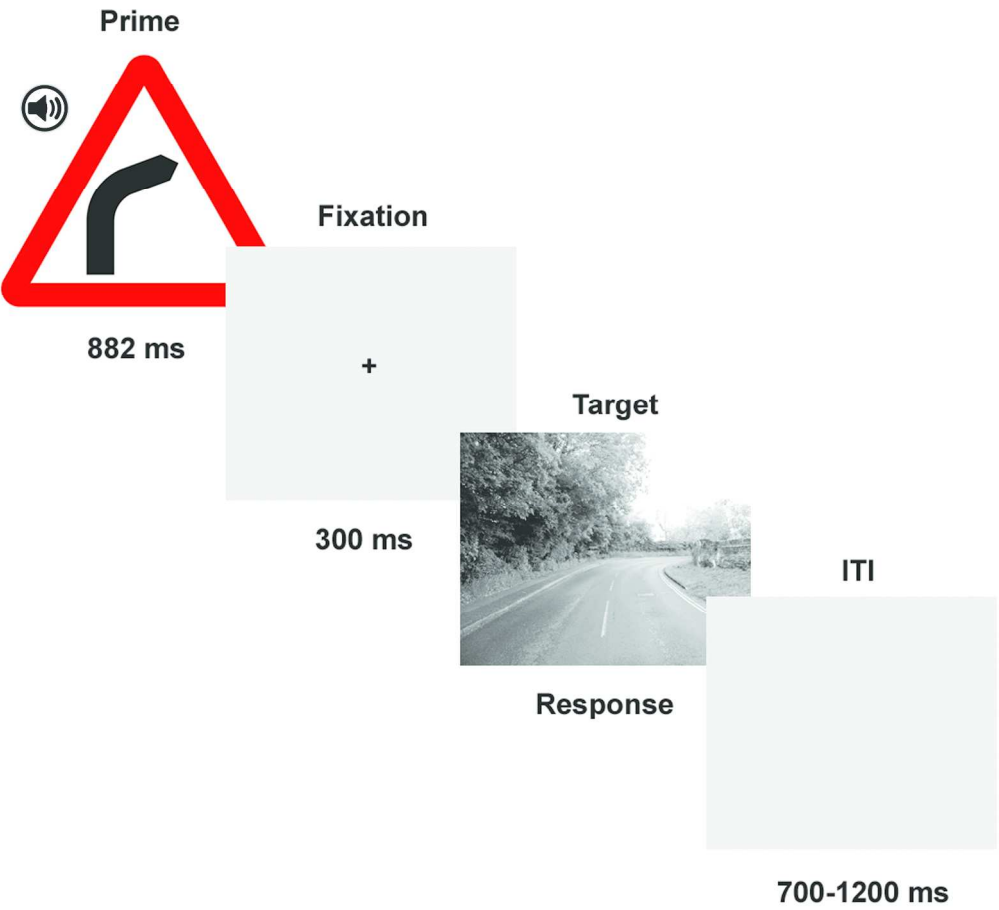


Figure 1: Sequence of trial events. Primes were either visual (road sign), audio (computerised voice), or both (as illustrated in this example).
364x346mm (300 x 300 DPI)

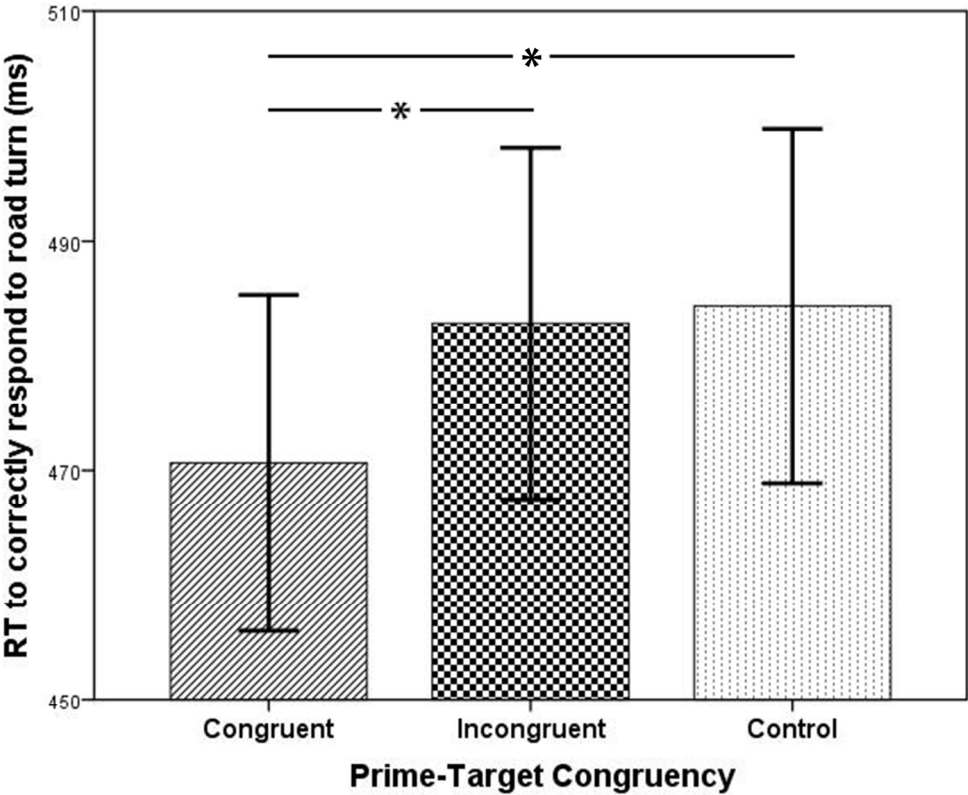


Figure 2: Mean response times to correctly respond to a road turn when the prime stimulus was congruent (diagonal lines) or incongruent (checker) to the target road turn direction, or a control (dots). Error bars represent the standard error of the mean.

176x141mm (300 x 300 DPI)

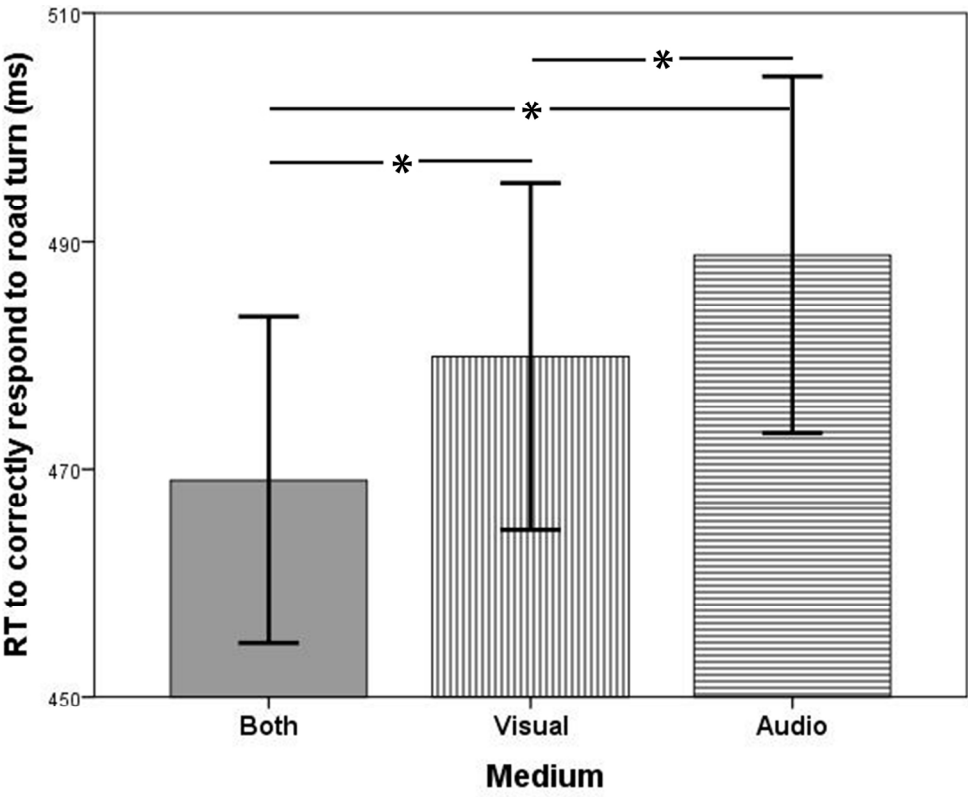


Figure 3: Mean response times to correctly respond to a road turn when the prime stimulus was multisensory (solid grey), visual (vertical lines) or audio (horizontal lines). Error bars represent the standard error of the mean.

176x141mm (300 x 300 DPI)

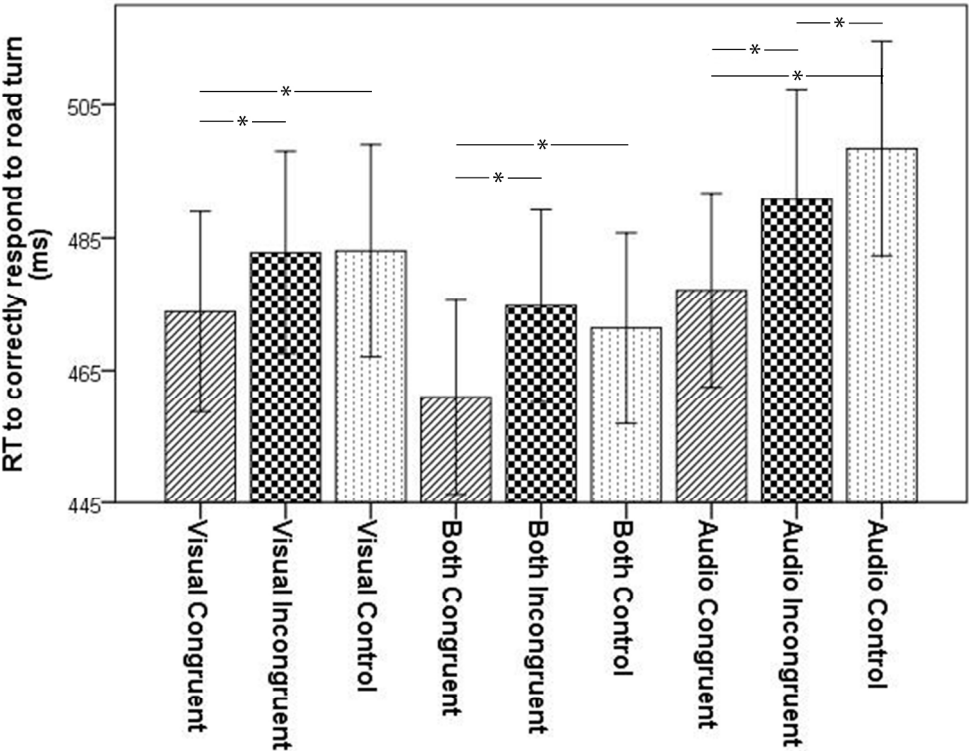


Figure 4: Mean response times to correctly respond to a road turn following a visual prime, multisensory prime or an audio prime when the prime stimulus was congruent (diagonal lines) or incongruent (checker) to the target road turn direction, or a control (dots). Error bars represent the standard error of the mean.

220x176mm (300 x 300 DPI)